

Introduction

This guide describes using the VM-550FF 1-watt, and the Loc3-5Tx 5-watt transmitters to locate the pushrod cable on the Type-MX and Type-CP cable reels. The locator being used is the vLoc3-Cam receiver, but users of the full range of Vivax-Metrotech locators will also find it useful.

Transmitter Operational Controls

The VM-550FF Transmitter is a multi-frequency 1-watt transmitter. The FF and two low frequencies are not relevant for this application; only the high frequency of 83kHz should be used. The locate frequency is applied by direct connection or induction. For this application, the direct connection method must be used.

VM-550FF What's in the box



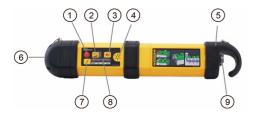
VM-550FF Connection Block



- VM-550FF Transmitter 1
- 2. Ground stake
- 3. Direct connection lead
- 4. Transmitter carry strap
- 5. 4 x D Cell alkaline batteries



VM-550FF Overview



Socket cover

- On/Off button 1.
- 2. Output power select and indicator

Direct connection socket

- 3. Speaker volume select
- 4. Speaker

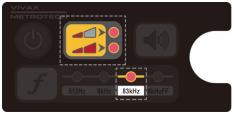
1.

2

- 5. Battery housing cover
- 6. Connection lead socket
- 7. Frequency select
- 8. Frequency selected indicators
- 9. Battery cover retaining screws

VM-550FF Keypad

For the purpose of locating the pushrod cable deployed in a pipe or locating a utility, only the 83kHz frequency and hi/low power options need be used.



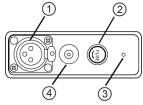


The Loc3-5Tx Transmitter is a multi-frequency 5-watt transmitter. When using this model transmitter, only frequencies above 65kHz should be used. The locate frequency can be applied by direct connection or induction. For this application, **the direct connection method** must be used.

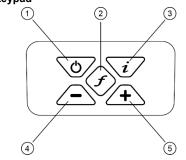
Loc3-5Tx What's in the box



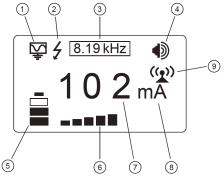
Loc3-5Tx Connections Block



Loc3-5Tx Keypad



Loc3-5Tx Display



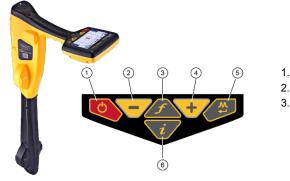
- 1. Loc3 series transmitter
- 2. Ground stake
- 3. Direct connection lead
- 4. 8 x D cell alkaline batteries
- 5. Alkaline battery tray
- 6. Mini-USB lead

- 1. Connection lead socket
- 2. Fuse (1.6A/250V Fuse)
- 3. Loudspeaker
- 4. Battery charging socket & DC input
- 1. On/Off control
- 2. Frequency select
- 3. Information (Volume, LCD contrast, Frequency menu)
- 4. Output decrease (Navigate through the menu)
- 5. Output increase (Navigate through the menu)
- 1. Mode indication icon
- 2. High Voltage Warning (output is enabled for high voltage)
- 3. Frequency being transmitted
- 4. Loudspeaker level
- 5. Battery status
- 6. Output setting
- 7. Digital readout (mA, volts, ohms)
- 8. Units (mA, volts, ohms)
- 9. Tx-Link status





vLoc3-Cam Receiver



- On/Off
- Reduce sensitivity
- 3. Select frequency
- 4. Increase sensitivity
- 5. Mode select
- 6. Depth readings

Active Location of the Camera Pushrod Cable

Locating the route of the deployed pushrod cable is possible with the use of a transmitter, which will apply a precise locate signal to one of the pushrod cables conductors. The locate signal is applied by directly connecting the transmitter to the connection post of the Type-CP or Type-MX pushrod cable reels. The picture below shows a direct connection post that the red transmitter lead connects to. The VM-550FF is a good choice of a transmitter, providing 83kHz at 1 watt of power. However, any transmitter with a high direct connection frequency over 65kHz is suitable for the task.



Pushrod Trace Post

Peak Response Mode Λ

The Line mode used to locate the pushrod cable is known as a Peak Response mode. Two horizontal antennas provide a "Peak" or maximum signal response when over the center of the pushrod cable. The below illustration provides an example of a Peak locate signal.



The left illustration shows a low bar graph in blue and low signal strength of 18.3 when approaching the pushrod cable from right to left, The center illustration shows the highest bar graph response and signal strength of 61.4 when directly over the pushrod cable, The right illustration shows a low bar graph and low signal strength of 18.3 after crossing the pushrod cable and now to the left of it.

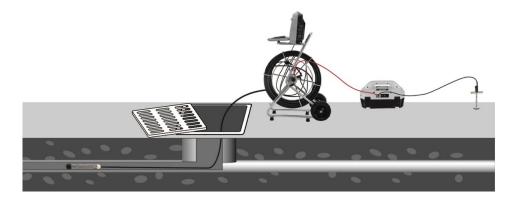




Method:

- Applying a signal
 - 1. Connect the red lead to the reels connection post.
 - 2. Connect the black lead to a suitable ground such as a ground stake inserted in the soil. If possible, place the ground stake at right angles to the suspected pipe direction as the earth lead may interfere with signals coming from the Pushrod cable.

 $\overset{\hbox{\tiny em}}{\longrightarrow}$ Make sure the leads are not going to impede the operation of the turning pushrod cable cage.



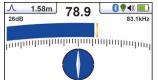
^{dd} If there is not a suitable area to insert the ground rod into the earth, it may be that the manhole access point has a metal surround around the hole. It should be possible to make a good connection by clipping onto the surround. If the surround is rusty, use a wire brush to clean the connection point first.

- 3. Select 83.1kHz frequency on the transmitter. (If 83.1kHz is not available on the transmitter, select 65kHz or 32.8kHz)
- 4. Insert the pushrod into the pipe and push in at least 5m (15ft) of the pushrod cable. (less than this may not provide enough signal)

• Locating the Pushrod Cable

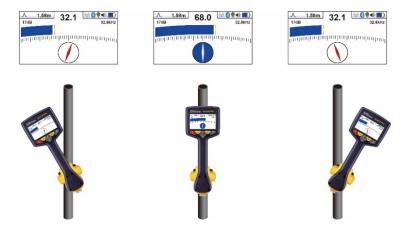
(connect to the reel as described above)

5. Use the "Mode" button to choose the Line mode. The peak icon Λ should be showing in the top left portion of the screen, and the screen should look similar to the illustration below.



6. Use the "f" button to set the locators frequency to that of the transmitter.

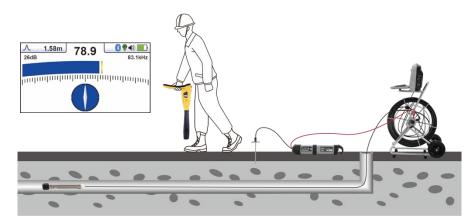
Whote that the screen will now show the addition of a compass (line direction indicator). In the presence of a locate signal, the compass will align itself parallel to the pushrod cable being located. When the compass indicator is parallel to the pushrod cable, the circle will be filled in blue. This ensures that the operator is aware of the direction of the pushrod cable.



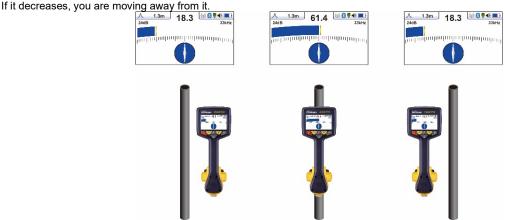
7. Stand approximately 5m (6ft) from the reel and over the suspected position of the pushrod cable.







- 8. Hold the locator vertically and rotate it on its axis until the compass indicates Forward/Back and is filled in blue color, as in the above illustration.
- 9. Adjust the sensitivity control, using the "+" and "-" keys, so that the bar graph is at approximately 50%.
- 10. Keeping the vLoc3-Cam vertical, move to the side slightly. If the bar graph increases, you are moving toward the pushrod cable.



Make the compass indicator in line and leave it blue.

- 11. Move toward the pushrod cable until a maximum "Peak" signal is obtained. It may be necessary to reduce or increase the sensitivity to keep the bar graph on the scale. This is normal and should be expected. Try to keep the vLoc3-Cam vertical and avoid swinging it as swinging may create false readings.
- 12. Move the locator side to side to ensure a maximum signal is detected. Use the peak level indicator to assist.



- 13. With the maximum signal found and the compass running Forward/Back, the vLoc3-Cam is now directly over the pushrod cable and exactly across it.
- 14. The depth is also displayed in the box at the top left of the screen unless a weak signal is detected. The depth is only accurate if the locator is directly above and in line with the pushrdo cable.





15. Continue to trace the pushrod cable along the route.

As the end of the pushrod cable is reached, the signal will rapidly reduce. This is to be expected and typically will happen a meter or two (3-6 feet) from the camera head.



At this point, the signal will start to be distorted, and the depth measurement will be affected. Check for distortion by raising the locator a known distance such as 300mm (1ft) and check the depth changes by approximately this amount. If it doesn't, treat the results with caution.

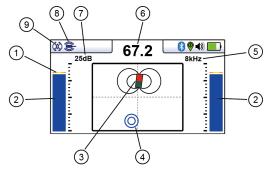
Distortion will also occur at the reel end of the pushrod cable.

If the exact position of the camera is required, switch the sonde on at the control box and use the vloc3-Cam in the sonde mode to detect the camera head (see section "Sonde Location Mode.")

Sonde Location Mode

The sonde is located at the spring termination end, where it connects to the pushrod cable. When activated in the control module, the sonde emits a locating signal that the vLoc3-Cam locator can detect and pinpoint.

Sonde screen icons:



- 1. Peak signal detector
- 2. Signal strength bar graph
- 3. Sonde icon
- 4. Null point
- 5. Frequency selection
- 6. Numeric signal level (mirrors the bar graph)
- 7. Gain setting
- 8. Sonde mode icon
- 9. Omni Peak response icon

Method

- 1. Activate the sonde from the control module. Push the sonde/camera head approximately 10 to 12 feet (3-4m) into the pipe.
- 2. Switch on the vLoc3-Cam locator and use the Mode key to enter the sonde mode. The sonde and omni peak icons will appear in the upper left corner of the LCD.
- 3. Use the "f" key to select the sonde frequency matching frequency of the control module.

^ஞ Tip

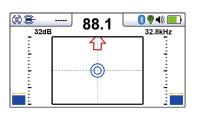
Use a low frequency such as 512 or 640Hz in ferrous pipe material such as is cast iron as low frequencies penetrate metal better than high frequencies. Also, use low frequencies when locating over re-bar as low frequencies are less likely to jump onto metal structures. Use higher frequencies such as 32.8kHz when in PVC, plastics, or clay pipes, as this will give steadier results.

- 4. Hold the locator vertically and stationary with the tip on the ground.
- 5. If the locator is within the range of the sonde, the screen will appear similar to the one below with an arrow pointing in a particular and steady direction. The bar graphs on either side of the screen are identical and indicate the signal strength. Use the + and keys to alter the receiver gain to keep the signal within the limits of the bar graph.

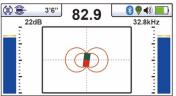


- 6. If the bar graph is not steady, it will most likely be because the sonde is not within range. In this case, hold the locator at approximately 45 degrees to the ground and rotate the locator around a full 360 degrees around you.
- 7. Note the direction of the strongest signal and walk towards it until the bar graph shows a steady signal. Now revert to step five above.
- 8. Slowly walk in the direction of the arrow.
- 9. A double circle will appear on the screen. This double circle indicates the position of a null signal. Walk toward it and position it over the crosshairs of the screen. Now rotate the locator so that the arrow is pointing forward.

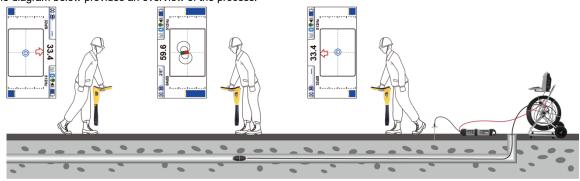




- 10. Keeping the null indicator on the vertical line, walk toward the arrow.
- 11. A Sonde icon will soon appear (Note that the arrow is not shown when the sonde icon appears). Keeping the locator vertical, carry on walking toward the Sonde until it is positioned on the crosshairs. The locator is now directly over the Sonde. Note that the depth of the sonde is also displayed.



12. The diagram below provides an overview of the process:



Overview

- 13. Note that when directly over the Sonde, it may be necessary to confirm the position of the Sonde, left to right. Do this by moving the locator left to right to identify the location of the strongest signal, as indicated on the bar graph. At this time, the depth to the Sonde will be displayed at the top of the display.
- 14. Having pinpointed the position of the Sonde/camera head, it can now be pushed into a new location, and the process repeated. It is advisable to keep the survey intervals too short distances such as six feet (two meters) as this makes the process of locating easier.

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